Discrete Flavor Symmetries in D-brane models

fernando marchesano



What does String Theory has to say about flavor?

Hierarchies in mass matrices

example: F-theory GUTs

Diego & Gianluca's talks

✦ Flavor symmetries

in particular discrete flavor symmetries

Reviews: Ishimori et al'10 Altarelli & Feruglio'10

Discrete flavor symmetries are used in BSM model building to

- Explain quark textures and lepton masses and mixings
- Avoid FCNC in the MSSM

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in particular discrete flavor symmetries

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Questions:

How generic are discrete flavor symmetries in s.t.? What is their origin? 4d field theory description? Which kind of groups & reps appear?

- To answer these questions, we must learn to realize discrete symmetries in string theory
- However, quantum gravity does not seem to like global symmetries
 - microscopic arguments in string theory

see e.g. Banks & Seiberg'11 Banks & Dixon'88

general arguments in black hole evaporation

and so, in the context of string theory in order to realize exact symmetries one should look for discrete gauge symmetries

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general arguments in black hole evaporation

and so, in the context of string theory in order to realize exact symmetries one should look for discrete gauge symmetries

- Examples in the literature:
 - ◆ Z_N symmetries \subset anomalous U(1)'s
 - Compactifications with fluxes
 - Compactifications with torsion cycles

coming soon

Mikel's talk

Cámara, Ibáñez, 7.M. 11

see e.g. Banks & Seiberg'11

Banks & Dixon'88

Semi-realistic D-brane models generically contain U(1) gauge symmetries beyond U(1)_Y



- Semi-realistic D-brane models generically contain U(1) gauge symmetries beyond U(1)_Y
- Most of them acquire a mass via a Stückelberg mechanism

$$\mathcal{L} \supset kB \wedge F \quad \Rightarrow \quad \mathcal{L}_{Stk} = \frac{1}{2} (d\phi + kA)^2 \qquad (d\phi = *_4 dB)$$
$$\Rightarrow \quad M_{U(1)} \sim M_s$$

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Such symmetries are broken by D-brane instantons, which generate effective couplings forbidden by the U(1) symmetry

$$W \sim \Phi^{nk} e^{-2\pi nT}$$
 $T = \rho + i\phi$ invariant $A \rightarrow A + d\lambda$
under $T \rightarrow T + ik\lambda$

Mechanism to generate suppressed couplings (Yukawas, neutrino Majorana masses ...) Blumenhagen, Cvetic, Weigand '06 Ibáñez & Uranga '06

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✤ However, if k is non-trivial, they still have to preserve a residual Z_k gauge symmetry ⇒ some couplings are forbidden at all levels

Berasaluce-Gouzález et al. '11

Couplings and symmetries

- Consequence: The symmetries of a compactification and their nature are relevant for the structure of couplings in the effective theory.
- Previous example: D-brane U(1) symmetries are made massive by a Stückelberg mechanism, only broken by non-perturbative effects
 → to a subgroup Z_N



Discrete Gauge Symmetries in 4d QFT

***** Basic Lagrangian for a \mathbb{Z}_k gauge symmetry

$$\mathcal{L} = \frac{1}{2} (d\phi - kA)^2 - \frac{1}{4} F_{\mu\nu} F^{\mu\nu}$$

 $\phi \sim \phi + 1$

axion

Gauging of a shift symmetry by a U(1)

 $A_{\mu} \to A_{\mu} + \partial_{\mu}\lambda \qquad \phi \to \phi + k\lambda$

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Dual description:

$$\mathcal{L}' = \frac{1}{2}H \wedge *H + \mathbf{k}B \wedge F + \frac{1}{2}F \wedge *F \qquad (d\phi = *_4 dB)$$

we can read the remaining \mathbb{Z}_k symmetry from the coefficient of the BF coupling Banks & Seiberg '11

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On the other hand, we can interpret k as a winding number between the S¹ = R / Γ, where the axion lives and the U(1) = S¹ = R / Γ' of the gauge theory

Discrete gauge symmetry =
$$\frac{\Gamma}{\Gamma'} = \mathbf{Z}_k$$
 $A \to A + d\lambda$; $\phi \to \phi + n\lambda$
 $\phi \to \phi + 1$

= identifications of ϕ not taken into account by the gauge symmetry

Multiple Abelian case:

$$(\partial_{\mu}\phi^{a} - k_{i}^{a}A_{\mu}^{i})(\partial_{\nu}\phi^{b} - k_{i}^{b}A_{\nu}^{i})\eta^{\mu\nu}\delta_{ab}$$
$$P = \frac{\Gamma}{\Gamma'} \rightarrow |P| = \det k$$



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Non-Abelian case:



 Axion-like scalars with non-commuting shift symmetries

 $\partial_{\mu}\phi^{a}\partial^{\mu}\phi^{b}G_{ab}(\phi) \qquad \phi^{b} \to \phi^{b} + \epsilon^{A}X_{A}^{b} \qquad [X_{A}, X_{B}] = f_{AB}^{C}X_{C}$

Axionic manifold \rightarrow group manifold or quotient by discrete subgroup M/ Γ

• Gauging of the axionic manifold: $\partial_{\mu}\phi^{a} \rightarrow \partial_{\mu}\phi^{a} - k_{i}^{a}A_{\mu}^{i}$

• Discrete gauge symmetry again given by: $P = \frac{\Gamma}{\Gamma'}$

An example

Simple example: Heisenberg group *H*₃

$$[X_1, X_2] = X_3$$

Axionic Lagrangian:

$$G_{ab}(\phi)\partial_{\mu}\phi\partial^{\mu}\phi = \mathcal{K}_{ab}\eta^{a}_{\mu}\eta^{b\,\mu} \qquad \qquad \eta^{1}_{\mu} = \partial_{\mu}\phi^{1} \qquad \eta^{2}_{\mu} = \partial_{\mu}\phi^{2} \\ \eta^{3}_{\mu} = \partial_{\mu}\phi^{3} + \frac{1}{2}(\phi^{1}\partial_{\mu}\phi^{2} - \phi^{2}\partial_{\mu}\phi^{1})$$

♦ \mathcal{H}_3 non-compact but \mathcal{H}_3/Γ compact → twisted 3-torus

$$\Gamma: \left\{ \begin{array}{ll} \phi^1 \to \phi^1 + 1 & \phi^3 \to \phi^3 - \frac{\phi^2}{2} \\ \phi^2 \to \phi^2 + 1 & \phi^3 \to \phi^3 + \frac{\phi^1}{2} \\ \phi^3 \to \phi^3 + 1 \end{array} \right.$$

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◆ Upon gauging: P = ^Γ/_{Γ'} = (**Z**_k × **Z**_k) ⋊ **Z**_k
◆ k=2 → P = D₄ T^k₁ = T^k₂ = T^k₃ = 1

♦ k=3 → P = Δ (27) $T_1 T_2 = T_3 T_2 T_1$

Discrete Flavor Symmetries from D-branes

DFS & intersecting branes

- The discrete symmetries obtained from anomalous U(1)'s are Abelian and flavor-independent
- One may however also obtain flavor discrete symmetries. These symmetries may be non-Abelian and contain the previous Abelian symmetries as a subgroup.
- Simple mechanism for family replication: intersecting D-branes



Simplest case: intersecting D6-branes on T²xT²xT²





$$\begin{cases} V_{\mu}^{x} \sim g_{\mu}^{x} \\ V_{\mu}^{y} \sim g_{\mu}^{y} \end{cases} \end{cases} \rightarrow \quad U(1) \times U(1)$$

Simplest case: intersecting D6-branes on T²xT²xT²





$$\begin{cases} V_{\mu}^{x} \sim g_{\mu}^{x} \\ V_{\mu}^{y} \sim g_{\mu}^{y} \end{cases} \end{cases} \rightarrow \qquad U(1) \times \mathbb{Z}_{q}$$
$$\mathcal{L}_{\mathrm{St}} = \frac{1}{2} \left(\partial_{\mu} \phi_{a} - m_{a} V_{\mu}^{x} + n_{a} V_{\mu}^{y} \right)^{2}$$

Simplest case: intersecting D6-branes on T²xT²xT²





$$\begin{cases}
 V_{\mu}^{x} \sim g_{\mu}^{x} \\
 V_{\mu}^{y} \sim g_{\mu}^{y}
 \end{cases} \right\} \rightarrow P = \mathbb{Z}_{I_{ab}}$$

$$\mathcal{L}_{St} = \frac{1}{2} \left(\partial_{\mu} \phi_{a} - m_{a} V_{\mu}^{x} + n_{a} V_{\mu}^{y} \right)^{2} \\
 + \frac{1}{2} \left(\partial_{\mu} \phi_{b} - m_{b} V_{\mu}^{x} + n_{b} V_{\mu}^{y} \right)^{2}$$

Simplest case: intersecting D6-branes on T²xT²xT²



On each T²

 \boldsymbol{y}



Simplest case: intersecting D6-branes on T²xT²xT²





$$\begin{cases}
 V_{\mu}^{x} \sim g_{\mu}^{x} \\
 V_{\mu}^{y} \sim g_{\mu}^{y}
 \end{cases} \rightarrow P = \mathbb{Z}_{d} \\
 d = \text{g.c.d.}(I_{ab}, I_{bc}, I_{ca})
 \end{cases}$$

$$\mathcal{L}_{\text{St}} = \frac{1}{2} \left(\partial_{\mu} \phi_{a} - m_{a} V_{\mu}^{x} + n_{a} V_{\mu}^{y} \right)^{2} \\
 + \frac{1}{2} \left(\partial_{\mu} \phi_{b} - m_{b} V_{\mu}^{x} + n_{b} V_{\mu}^{y} \right)^{2} \\
 + \frac{1}{2} \left(\partial_{\mu} \phi_{c} - m_{c} V_{\mu}^{x} + n_{c} V_{\mu}^{y} \right)^{2}$$

Simplest case: intersecting D6-branes on T²xT²xT²





$$\left. \begin{array}{c} B^x_{\mu} \sim B_{\mu x} \\ B^y_{\mu} \sim B_{\mu y} \end{array} \right\} \rightarrow \quad U(1) \times U(1)$$

Simplest case: intersecting D6-branes on T²xT²xT²





$$\left. \begin{array}{l} B^x_{\mu} \sim B_{\mu \, x} \\ B^y_{\mu} \sim B_{\mu \, y} \end{array} \right\} \rightarrow \quad U(1) \times \mathbb{Z}_q$$
$$\mathcal{L}_{\mathrm{St}} = \frac{1}{2} \left(\partial_{\mu} \xi_a - n_a B^x_{\mu} - m_a B^y_{\mu} \right)^2$$

Simplest case: intersecting D6-branes on T²xT²xT²





Simplest case: intersecting D6-branes on T²xT²xT²



On each T²

 \boldsymbol{y}



Simplest case: intersecting D6-branes on T²xT²xT²



$$y \qquad B_{\mu}^{x} \\ B_{\mu}^{y} \\ B_{\mu}^{y} \\ \mathcal{L}_{St} = \begin{cases} \\ n_{a}, m_{a} \end{pmatrix} = (1, 3) \\ (n_{b}, m_{b}) = (1, 0) \end{cases} + \frac{1}{2}$$

$$\begin{aligned}
 B_{\mu}^{x} \sim B_{\mu x} \\
 B_{\mu}^{y} \sim B_{\mu y}
 \end{aligned}
 \right\} \rightarrow P = \mathbb{Z}_{d} \\
 d = \text{g.c.d.}(I_{ab}, I_{bc}, I_{ca}) \\
 \mathcal{L}_{\text{St}} = \frac{1}{2} \left(\partial_{\mu} \xi_{a} - n_{a} B_{\mu}^{x} - m_{a} B_{\mu}^{y} \right)^{2} \\
 + \frac{1}{2} \left(\partial_{\mu} \xi_{b} - n_{b} B_{\mu}^{x} - m_{b} B_{\mu}^{y} \right)^{2} \\
 + \frac{1}{2} \left(\partial_{\mu} \xi_{c} - n_{c} B_{\mu}^{x} - m_{c} B_{\mu}^{y} \right)^{2}
 \end{aligned}$$

Flavor group from each T²





Flavor group from each T²



This flavor group constrains the Yukawa couplings:



Magnetized D-branes

Dual example: U(1) gauge theory compactified on T², with a gauge field strength background in the extra dimensions

$$F_2 = 2\pi M dx \wedge dy \quad \Rightarrow \quad A = \pi M (x dy - y dx)$$

The magnetization breaks (gauges) the translational isometry, because A changes as we move on T²

$$A(x + \lambda_x, y) = A(x, y) + \pi M \lambda_x dy$$
$$A(x, y + \lambda_y) = A(x, y) - \pi M \lambda_y dx$$



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$$e^{\lambda_j D_j} i D_k e^{-\lambda_j D_j} = i D_k + \lambda_j F_{jk}$$
$$e^{\mu_j B_j} i D_k e^{-\mu_j B_j} = i D_k + \mu_j \delta_{jk}$$

$$\mathcal{L}_{St} = -\frac{1}{2} \sum_{\alpha=a,b} \left\{ \left(\partial_{\mu} \xi_{x,\alpha} + m_{\alpha} V^{y}_{\mu} - B^{x}_{\mu} \right)^{2} + \left(\partial_{\mu} \xi_{y,\alpha} - m_{\alpha} V^{x}_{\mu} - B^{y}_{\mu} \right)^{2} \right\}$$
$$e^{\frac{D_{x}}{M}} \psi^{j} \rightarrow e^{2\pi i \frac{j}{M}} \psi^{j}$$
$$e^{\frac{D_{y}}{M}} \psi^{j} \rightarrow \psi^{j+1}$$

 \Rightarrow

discrete Heisenberg flavor symmetry

(twisted torus isometries)

Beyond tori

This is all very nice, but T⁶ is not a good example of compactification manifold because one cannot build stable chiral D-brane models.

- One should add O-planes
- One should add curvature \rightarrow generic CY (example: T^{6}/Γ)
- Problem: CY's do not have continuous isometries, so we cannot apply our 4d calculations to find the flavor group

Beyond tori

This is all very nice, but T⁶ is not a good example of compactification manifold because one cannot build stable chiral D-brane models.

- One should add O-planes
- One should add curvature \rightarrow generic CY (example: T^{6}/Γ)
- Problem: CY's do not have continuous isometries, so we cannot apply our 4d calculations to find the flavor group
- Idea: Revisit T² case and understand flavor group in terms of symmetries



 $U(1) \times U(1) \to \mathbb{Z}_3$ $\mathbf{P}^{\text{bulk}} \to \mathbf{P}^{\text{bulk+brane}}$

Apply the same for CY or T⁶/Γ

Discrete Flavor Symmetries in orbifolds

Blumenhagen, Cvetic, F.M., Shiu. '05

Dudas. Tirmigaziu'05

- Simple example of orbifold: T⁶/Z₂xZ₂
 - Allows for chiral N=1 models
 - Allows for D-branes with no moduli
- Isometry group broken to Z₂⁶ by the orbifold action
- Rigid D6-branes go through fixed points





Breaking pattern for isometries on T²/Z₂

$$\mathbb{Z}_2 \times \mathbb{Z}_2 \to \mathbb{Z}_2 \to \mathbb{Z}_2 \to \mathbb{Z}_2$$

$$\mathbb{Z}_2 \times \mathbb{Z}_2 \to \mathbb{Z}_2$$

$$\mathbb{Z}_2 \to \mathbb{Z}_2$$

- The same applies to the B-field transformations
- Final flavor group: $H_2 \simeq D_4$
- For T⁶/Z₂xZ₂: $\mathbf{P} = D_4^{[d_1-1]} \times D_4^{[d_2-1]} \times D_4^{[d_3-1]}$

 $d_i = \text{g.c.d.}(2, I^i_{ab}, I^i_{bc}, I^i_{ca}, \dots)$

If in a T^2 all intersection numbers are even we have a D₄ factor

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If in a T^2 all intersection numbers are even we have a D₄ factor

Remarks:

• D6-branes through same fixed points \leftrightarrow twisted tadpoles

• I_{ab} = even does not imply even number of families



$$\begin{split} \psi^{j}_{\text{even}} &= \psi^{j,N} + \psi^{N-j,N} \\ \psi^{j}_{\text{odd}} &= \psi^{j,N} - \psi^{N-j,N} \end{split}$$

Representations:

$$\psi_{ab}^{j_1, j_2, j_3} \,=\, \psi_{ab}^{j_1} \cdot \psi_{ab}^{j_2} \cdot \psi_{ab}^{j_3}$$

$ I^i_{ab} $	$\psi_{\text{even}}^{j_i}$ dim = $ I_{ab}^i /2 + 1$	$\psi_{\text{odd}}^{j_i}$ dim = $ I_{ab}^i /2 - 1$
4s+2	$\oplus^{s+1}\mathbf{R}_2$	$\overset{s}{\oplus} \mathbf{R}_2$
8s + 4	$\stackrel{s+1}{\oplus} (+,+) \stackrel{s+1}{\oplus} (+,-) \stackrel{s+1}{\oplus} (-,+) \stackrel{s}{\oplus} (-,-)$	$\stackrel{s}{\oplus} (+,+) \stackrel{s}{\oplus} (+,-) \stackrel{s}{\oplus} (-,+) \stackrel{s+1}{\oplus} (-,-)$
8s+8	$\stackrel{s+2}{\oplus}(+,+)\stackrel{s+1}{\oplus}(+,-)\stackrel{s+1}{\oplus}(-,+)\stackrel{s+1}{\oplus}(-,-)$	$\stackrel{s}{\oplus} (+,+) \stackrel{s+1}{\oplus} (+,-) \stackrel{s+1}{\oplus} (-,+) \stackrel{s+1}{\oplus} (-,-)$



Examples

♣ 4-generation Pati-Salam from Blumenhagen, Cuetic, 7.M., Shiu. '05

N_{α}	(n^1_lpha,m^1_lpha)	(n_{lpha}^2,m_{lpha}^2)	(n_{lpha}^3,m_{lpha}^3)
$N_{a_1} = 4$	(1, 0)	(0, 1)	(0, -1)
$N_{a_2} = 2$	(1, 0)	(2, 1)	(4, -1)
$N_{a_3} = 2$	(-3,2)	(-2,1)	(-4, 1)

$$U(4) \times U(2)_L \times U(2)_R$$

$$\downarrow$$

$$SU(4) \times SU(2)_L \times SU(2)_R$$

Sector	Field	$D_4^{(1)}$	$D_4^{(2)}$	$D_4^{(3)}$
a_1a_2	$F_L=(4,ar{2},1)$	1	\mathbf{R}_2	(-,-)
$a_1 a'_2$	$F'_L = ({f 4},{f 2},{f 1})$	1	(-,-)	\mathbf{R}_2
$a_1 a_3$	$F_R = (\bar{4}, 1, 2)$	\mathbf{R}_2	\mathbf{R}_2	(-,-)
$a_2 a_3$	$H = (1, 2, \bar{2})$	\mathbf{R}_2	$1\oplus(+,-)\oplus(-,+)$	1
$a_2a'_3$	$H'=(1,\bar{2},\bar{2})$	\mathbf{R}_2	1	$1^2 \oplus (+,-) \oplus (-,+) \oplus (-,-)$

 $Y: (a_1a_2) \otimes (a_1a_3) \otimes (a_2a_3) \longrightarrow (\mathbf{4}, \mathbf{\bar{2}}, \mathbf{1}) \otimes (\mathbf{\bar{4}}, \mathbf{1}, \mathbf{2}) \otimes (\mathbf{1}, \mathbf{2}, \mathbf{\bar{2}})$

 $Y': (a'_1a_2) \otimes (a_1a_3) \otimes (a'_2a_3) \quad \longrightarrow \quad (\mathbf{4}, \mathbf{2}, \mathbf{1}) \otimes (\bar{\mathbf{4}}, \mathbf{1}, \mathbf{2}) \otimes (\mathbf{1}, \bar{\mathbf{2}}, \bar{\mathbf{2}})$

Examples

♣ 4-generation Pati-Salam from Blumenhagen, Cuetic, 7.M., Shin. '05

N_{α}	(n^1_lpha,m^1_lpha)	(n_{lpha}^2,m_{lpha}^2)	(n_{lpha}^3,m_{lpha}^3)
$N_{a_1} = 4$	(1, 0)	(0, 1)	(0, -1)
$N_{a_2} = 2$	(1, 0)	(2, 1)	(4, -1)
$N_{a_3} = 2$	(-3,2)	(-2,1)	(-4, 1)

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$$\downarrow$$

$$SU(4) \times SU(2)_L \times SU(2)_R$$

Sector	Field	$D_4^{(1)}$	$D_4^{(2)}$	$D_4^{(3)}$
a_1a_2	$F_L=(4,ar{2},1)$	1	\mathbf{R}_2	(-,-)
a_1a_2'	$F'_L = ({f 4},{f 2},{f 1})$	1	(-,-)	\mathbf{R}_2
$a_1 a_3$	$F_R = (ar{4}, 1, 2)$	\mathbf{R}_2	\mathbf{R}_2	(-,-)
$a_2 a_3$	$H = (1, 2, \bar{2})$	\mathbf{R}_2	$1 \oplus (+,-) \oplus (-,+)$	1
$a_2a'_3$	$H'=(1,\bar{2},\bar{2})$	\mathbf{R}_2	1	$egin{array}{c} 1^2 \oplus (+,-) \oplus (-,+) \oplus (-,-) \end{array}$

 $\begin{array}{ll}Y:(a_{1}a_{2})\otimes(a_{1}a_{3})\otimes(a_{2}a_{3})&\longrightarrow&(\mathbf{4},\bar{\mathbf{2}},\mathbf{1})\otimes(\bar{\mathbf{4}},\mathbf{1},\mathbf{2})\otimes(\mathbf{1},\mathbf{2},\bar{\mathbf{2}})&\longrightarrow&\text{only 3 indep couplings}\\Y':(a_{1}'a_{2})\otimes(a_{1}a_{3})\otimes(a_{2}'a_{3})&\stackrel{}{\text{torbull}}(\mathbf{4},\mathbf{2},\mathbf{1})\otimes(\bar{\mathbf{4}},\mathbf{1},\mathbf{2})\otimes(\mathbf{1},\bar{\mathbf{2}},\bar{\mathbf{2}})&\stackrel{}{\text{forbull}}\end{array}$

Examples

✤ 3-generation Pati-Salam

N_{α}	(n^1_α, m^1_α)	$(n_{\alpha}^2, m_{\alpha}^2)$		(n_{lpha}^3,m_{lpha}^3)				
$N_a = 4$	= 4 (1,0)		1, 1)	(1,-1)				
$N_b = 2$	(n, -3)	(0, 1)		(3, -1)				
$N_c = 2$	(l, -1)	(-2, 1)		(-1, -1)				
	¥							
Sector	Fields		D_4					
ab	$F_R = (ar{4}, ar{2}$, 1)	\mathbf{R}_2					
ab'	$F_R' = (\bar{4}, \bar{2})$, 1)	(-, -)					
ac	$F_L = (4, 1$	$,ar{2})$	\mathbf{R}_2					
ac'	$F'_L = (4, 1$, 2)	(+,+)					
bc	$H = (1, \bar{2},$	2)	(-, -	$)\oplus(-,-)$				
bc'	H' = (1 , 2	, 2)		$\stackrel{6}{\oplus} \mathbf{R}_2$				

 $U(4) \times U(2)_L \times U(2)_R$ \downarrow $SU(4) \times SU(2)_L \times SU(2)_R$

 $\begin{array}{rcl} Y:ab\otimes ac\otimes bc &\longrightarrow & (\bar{\mathbf{4}},\mathbf{2},\mathbf{1})\otimes (\mathbf{4},\mathbf{1},\bar{\mathbf{2}})\otimes (\mathbf{1},\bar{\mathbf{2}},\mathbf{2})\\ \\ Y':ab'\otimes ac\otimes bc' &\longrightarrow & (\bar{\mathbf{4}},\bar{\mathbf{2}},\mathbf{1})\otimes (\mathbf{4},\mathbf{1},\bar{\mathbf{2}})\otimes (\mathbf{1},\mathbf{2},\mathbf{2}). \end{array}$

8 indep couplings

Conclusions

- We have analyzed appearance of discrete flavor symmetries in D-brane models. In toroidal models, they can be read from BF couplings of closed string U(1)'s to open string axions.
- In orbifold models we need a new approach: we first consider the group P^{bulk} that leaves the closed string background invariant and then the subgroup P that also leaves D-branes invariant.

Conclusions

- We have analyzed appearance of discrete flavor symmetries in D-brane models. In toroidal models, they can be read from BF couplings of closed string U(1)'s to open string axions.
- In orbifold models we need a new approach: we first consider the group P^{bulk} that leaves the closed string background invariant and then the subgroup P that also leaves D-branes invariant.
- P will act non-trivially on open string zero modes and generate a non-Abelian flavor group → forbid Yukawa couplings beyond Z_k's. We can also define the approximate discrete symmetry P^{abc}
- We have analyzed the case of T⁶/Z₂xZ₂, obtaining a flavor group given by D₄ and tensor products of it.
- This definition of flavor group is quite general and can be applied to any manifold with discrete symmetries in the closed string sector, like e.g. smooth Calabi-Yau compactifications.